

PIERCING FAMILIES OF CONVEX SETS WITH d -INTERSECTION PROPERTY IN \mathbb{R}^d

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ABSTRACT. In this paper we consider finite families of convex sets in \mathbb{R}^d such that every d or less sets of the family have a common point. For some families of this type we give upper bounds on the size of a finite set intersecting all sets of the family.

1. INTRODUCTION

We consider finite families of convex sets in \mathbb{R}^d such that every d or less sets have a common point. We are interested in the minimal size of a finite set in \mathbb{R}^d having common point with every member of the family.

We begin with several definitions:

Definition. t -*transversal* for a family of sets \mathcal{F} is a set T of cardinality t such that $\forall S \in \mathcal{F} S \cap T \neq \emptyset$.

Definition. Minimal t such that a t -transversal of the family \mathcal{F} exists is called *transversal number* or *piercing number* of \mathcal{F} , and denoted $\tau(\mathcal{F})$.

Definition. A family of sets \mathcal{F} has *property* Π_k if for any nonempty $\mathcal{G} \subseteq \mathcal{F}$ such that $|\mathcal{G}| \leq k$ the intersection $\bigcap \mathcal{G}$ is not empty.

Helly's theorem states that Π_{d+1} implies $\tau(\mathcal{F}) = 1$ for any finite family \mathcal{F} of convex sets in \mathbb{R}^d .

We can see that the case of Π_d property in \mathbb{R}^d is the closest to the case of Helly's theorem, and we may expect reasonable upper bounds for $\tau(\mathcal{F})$ here. Of course, the example of hyperplanes in general position shows that Π_d property alone cannot guarantee any bound on $\tau(\mathcal{F})$. Hence we have to impose some limitations on family \mathcal{F} to obtain some bounds for the piercing number. In this paper we mostly consider families of homothets or translates of some compact convex set.

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From here on we consider finite families of closed convex sets in \mathbb{R}^d ($d \geq 2$) having property Π_d . We show that for certain families Π_d property implies $\tau(\mathcal{F}) \leq d + 1$. We also give a linear in d upper bound for the piercing number of families of euclidean balls in \mathbb{R}^d with Π_d property.

The simplest result of this type (Grünbaum's conjecture) was proved by the author in [4]:

Theorem 1. *Let \mathcal{F} be a family of translates of a two-dimensional convex compact set. If \mathcal{F} has property Π_2 then $\tau(\mathcal{F}) \leq 3$.*

In this paper we use the same main idea as in [4]. But the way of reasoning was quite cleared up, which lead to several more results.

Theorem 2. *Let \mathcal{F} be a family of homothets of a centrally symmetric convex compact set in \mathbb{R}^2 and let any two sets in \mathcal{F} be no more than two times different in size. If \mathcal{F} has property Π_2 then $\tau(\mathcal{F}) \leq 3$.*

In [3] Grünbaum proved the upper bound $\tau(\mathcal{F}) \leq 7$ without any size constraint. Theorem 2 gives less piercing number with size constraint. The bound $\tau(\mathcal{F}) \leq 3$ in this theorem is tight, it is well-known that it is tight even for families of equal unit disks.

Using the same technique we prove another result of this kind for euclidean balls in \mathbb{R}^d :

Theorem 3. *Let \mathcal{F} be a family of Euclidean balls in \mathbb{R}^d with radii no more than d times different. If \mathcal{F} has property Π_d then $\tau(\mathcal{F}) \leq d + 1$.*

The existence of $(d + 1)$ -transversal for a family of equal balls with Π_d property is proved in [1].

Theorem 3 generalizes this result for families of balls with size constraint. The author is not sure that the bound $\tau(\mathcal{F}) \leq d + 1$ in Theorem 3 is tight.

Using this result we can give an upper bound on the piercing number of a family of balls in \mathbb{R}^d with Π_d property without any size constraint:

Theorem 4. *Let \mathcal{F} be a family of Euclidean balls in \mathbb{R}^d . If \mathcal{F} has property Π_d then $\tau(\mathcal{F}) \leq 3(d + 1)$ when $d \geq 5$ and $\tau(\mathcal{F}) \leq 4(d + 1)$ when $d \leq 4$.*

It seems that the bound in this theorem can be improved, especially for small d . In case of $d = 2$ Theorem 4 gives $\tau(\mathcal{F}) \leq 12$, while Danzer's result (see [1, 2]) gives $\tau(\mathcal{F}) \leq 4$.

For a family of positive homothets of a simplex in \mathbb{R}^d we have bound $d + 1$ without size constraints:

Theorem 5. *Let \mathcal{F} be a family of positive homothets of a simplex in \mathbb{R}^d . If \mathcal{F} has property Π_d then $\tau(\mathcal{F}) \leq d + 1$.*

The author does not know whether Theorem 5 gives tight upper bound on the piercing number for $d > 2$. For $d = 2$ the bound is tight even for families of equal triangles. In this case the piercing problem is equivalent to the following covering problem: if every two points of a closed set $S \subset \mathbb{R}^2$ can be covered by a translate of triangle T , then S can be covered by 3 translates of T . Taking $S = -T$ we can see that 3 translates are necessary. Here the set S is infinite, but by the standard compactness reasoning some its finite subset still needs 3 translates of T to be covered.

Theorem 3 can be generalized to the case when the sets in the family do not have to be homothets of each other. We need some definitions to formulate the result.

Definition. A convex compact set in \mathbb{R}^d is called *R -upper convex* if it is an intersection of balls of radius R .

Definition. A convex compact set in \mathbb{R}^d is called *R -lower convex* if it is a union of balls of radius R .

Theorem 6. *Let \mathcal{F} be a family of convex compact sets in \mathbb{R}^d . Let every set in \mathcal{F} be R -lower convex and dR -upper convex for some constant $R > 0$. If \mathcal{F} has property Π_d then $\tau(\mathcal{F}) \leq d + 1$.*

The following question remains open: whether the upper bound $\tau(\mathcal{F}) \leq d + 1$ (or some other linear in d bound) is true for families of translates of a convex compact set.

2. SOME CONSEQUENCES OF Π_d PROPERTY

To prove theorems in this paper we explicitly construct a $(d + 1)$ -element set and prove that this is a transversal for \mathcal{F} .

This construction only uses Π_d property of some family \mathcal{F} of convex closed sets in \mathbb{R}^d , but it does not give a transversal of \mathcal{F} in the general case.

First we define a family of halfspaces that can test the non-existence of a common point of a family \mathcal{F} of compact convex sets.

Definition. Let $\{K_1, K_2, \dots, K_{d+1}\} \subseteq \mathcal{F}$. A family of halfspaces

$$\{H_1, H_2, \dots, H_{d+1}\},$$

where for any $i = 1, \dots, d + 1$ $K_i \subseteq H_i$ is called *test family of halfspaces* for family \mathcal{F} .

Definition. If a test family of halfspaces for \mathcal{F} has an empty intersection we call it *non-intersecting* test family of halfspaces.

We need some lemmas:

Lemma 1. *Let \mathcal{F} have Π_d property. Then for every non-intersecting test family of halfspaces $\{H_1, H_2, \dots, H_{d+1}\}$ for \mathcal{F} the set*

$$S(H_1, H_2, \dots, H_{d+1}) = \text{cl} \left(\mathbb{R}^d \setminus \bigcup_{i=1}^{d+1} H_i \right)$$

is a simplex.

Proof. The family $\mathcal{H} = \{H_1, H_2, \dots, H_{d+1}\}$ has empty intersection while every its proper subfamily have a common point. Let for $i = 1, \dots, d+1$

$$x_i \in \bigcap_{j \neq i} H_j.$$

If the points $\{x_i\}_{i=1}^{d+1}$ does not make a simplex then they lie in a $d-1$ -dimensional hyperplane and by the Radon's theorem the set of indices $[d+1]$ can be partitioned into I_1 and I_2 so that there exists

$$x \in \text{conv}\{x_i\}_{i \in I_1} \cap \text{conv}\{x_i\}_{i \in I_2},$$

but in this case $x \in \bigcap \mathcal{H}$.

Hence $\{x_i\}_{i=1}^{d+1}$ make a simplex S and halfspaces H_i contain its respective facets. If the family \mathcal{H} cover S then by Sperner's lemma $\bigcap \mathcal{H} \cap S \neq \emptyset$, which is not true. Thus we have a point

$$x \in \text{int } S \quad \forall i = 1, \dots, d+1 \quad x \notin H_i.$$

Consider some $y \in \mathbb{R}^d \setminus S$. If y is not contained in any halfspace of \mathcal{H} then the segment $[x, y]$ does not intersect any halfspace of \mathcal{H} (this is true because the complement to a halfspace is convex). Hence $z = [x, y] \cap \text{bd } S$ is not contained in any of \mathcal{H} , This is a contradiction with the fact that $\text{bd } S$ is covered by \mathcal{H} .

So we have $\mathbb{R}^d \setminus S \subseteq \bigcup \mathcal{H}$ and $S(H_1, H_2, \dots, H_{d+1}) = \text{cl} \left(\mathbb{R}^d \setminus \bigcup_{i=1}^{d+1} H_i \right)$ is a polytope with nonempty interior and $d+1$ facets, so it has to be a d -dimensional simplex. \square

Lemma 2. *If a family \mathcal{F} with Π_d property does not have non-intersecting test family of halfspaces then $\bigcap \mathcal{F} \neq \emptyset$.*

Proof. If $|\mathcal{F}| \leq d$ the statement is obvious.

Otherwise, by Helly's theorem we find $\mathcal{K} = \{K_1, K_2, \dots, K_{d+1}\} \subseteq \mathcal{F}$ such that $\bigcap \mathcal{K} = \emptyset$.

Let for $i = 1, \dots, d + 1$ L_i denote the set of linear functions $l(x)$ such that $l(x) \leq 0$ for all $x \in K_i$. By the standard properties of convex duality, if $\bigcap \mathcal{K} = \emptyset$ then the constant function $l(x) \equiv 1 \in \text{conv} \bigcup_{i=1}^{d+1} L_i$. Equivalently, there are non-negative numbers $\{a_i\}_{i=1}^{d+1}$ and functions $\{l_i\}_{i=1}^{d+1}$ ($l_i \in L_i \forall i = 1, \dots, d + 1$) such that

$$1 = \sum_{i=1}^{d+1} a_i l_i(x).$$

Denote $H_i = \{x : l_i(x) \leq 0\}$. These sets have no common point since in the common point the above equality cannot hold. For all $i = 1, \dots, d + 1$ $K_i \subseteq H_i$ and each H_i is either a halfspace or coincides with the whole \mathbb{R}^d . If we substitute those H_i 's that are equal to \mathbb{R}^d by arbitrary halfspaces containing respective K_i 's, we obtain a non-intersecting test family of halfspaces. \square

Lemma 3. *Let the family \mathcal{F} have Π_d property. Then either $\tau(\mathcal{F}) = 1$ or there exists such a non-intersecting test family of halfspaces $\{H_1, H_2, \dots, H_{d+1}\}$ that the volume of $S(H_1, H_2, \dots, H_{d+1})$ is maximal over all non-intersecting test families of halfspaces.*

Proof. If there is no non-intersecting test family of halfspaces then by Lemma 2 $\tau(\mathcal{F}) = 1$.

In the other case it is sufficient to show that for every fixed subfamily

$$\mathcal{K} = \{K_1, K_2, \dots, K_{d+1}\} \subseteq \mathcal{F}$$

with empty intersection the maximum of $\text{vol} S(H_1, H_2, \dots, H_{d+1})$ over all non-intersecting test families $\mathcal{H} = \{H_1, H_2, \dots, H_{d+1}\}$ corresponding to \mathcal{K} is reached. This is sufficient to prove the lemma since the number of subfamilies \mathcal{K} is finite.

Any d sets of family \mathcal{K} have nonempty intersection, so we find for all $i = 1, \dots, d + 1$

$$x_i \in \bigcap_{j \neq i} K_j.$$

As in the proof of Lemma 1

$$S(H_1, H_2, \dots, H_{d+1}) \subseteq \text{conv}\{x_1, x_2, \dots, x_{d+1}\},$$

hence $\text{vol}(S(H_1, H_2, \dots, H_{d+1}))$ is bounded.

It is clear that if we take instead of H_i the unique inner support halfspace for K_i contained in H_i the volume of $S(H_1, H_2, \dots, H_{d+1})$ becomes larger. Every support halfspace of K_i is determined by its unit normal vector n_i , so the variety of the families of support halfspaces to the sets of \mathcal{K} has the topology of a cartesian product of $d + 1$ unit spheres. We

consider the subset X of this space that corresponds to non-intersecting test families for \mathcal{K} . The vertices of $S(H_1, H_2, \dots, H_{d+1})$ and its volume are continuous functions on X .

Let $\sup_X \text{vol}(S(H_1, H_2, \dots, H_{d+1})) = 2\varepsilon > 0$. Then we can easily check that the variety of non-intersecting test families $\mathcal{H} = \{H_1, H_2, \dots, H_{d+1}\}$ such that

$$\text{vol}(S(H_1, H_2, \dots, H_{d+1})) \geq \varepsilon$$

is closed, hence the volume takes its maximum value 2ε at some point of X . \square

The above lemmas allow us to make a definition:

Definition. Let \mathcal{F} be a finite family of convex closed sets in \mathbb{R}^d with Π_d property and let $\bigcap \mathcal{F} = \emptyset$. Denote the simplex $S(H_1, H_2, \dots, H_{d+1})$ with maximal volume for some non-intersecting test family of half-spaces $\{H_1, H_2, \dots, H_{d+1}\}$ by $S(\mathcal{F})$. Denote the convex hull of the mass centers of facets of $S(\mathcal{F})$ by $s(\mathcal{F})$.

The importance of these simplices is explained by the following lemma:

Lemma 4. *Let \mathcal{F} be a finite family of convex closed sets in \mathbb{R}^d with Π_d property having no common point. In this case for any $S \in \mathcal{F}$ $S \cap s(\mathcal{F}) \neq \emptyset$.*

To prove Lemma 4 we need another lemma:

Lemma 5. *Let S be a simplex in \mathbb{R}^d with vertices $\{v_1, v_2, \dots, v_{d+1}\}$, let S' be a simplex with vertices $\{v'_1, v'_2, \dots, v'_d, v_{d+1}\}$. Let points v'_i ($i = 1, \dots, d$) lie on the rays $v_{d+1}v_i$ respectively. If $\text{int } S'$ contains the mass center of $\{v_1, \dots, v_d\}$ then $\text{vol } S' > \text{vol } S$.*

Proof. Take a coordinate frame with origin v_{d+1} and base

$$\{v'_1 - v_{d+1}, v'_2 - v_{d+1}, \dots, v'_d - v_{d+1}\},$$

let i -th coordinate of v_i be x_i . If $\text{int } S'$ contains the mass center of $\{v_1, \dots, v_d\}$ then

$$\sum_{i=1}^d x_i < d,$$

and by the mean inequality $\prod_{i=1}^d x_i < 1$, which implies $\text{vol } S' > \text{vol } S$. \square

Proof of Lemma 4. Consider the subfamily

$$\mathcal{K} = \{K_1, K_2, \dots, K_{d+1}\} \subseteq \mathcal{F},$$

corresponding to the non-intersecting test family of halfspaces

$$\mathcal{H} = \{H_1, H_2, \dots, H_{d+1}\},$$

where $S(\mathcal{F}) = S(H_1, H_2, \dots, H_{d+1})$. Denote the respective vertices of $S(\mathcal{F})$ and $s(\mathcal{F})$ by $\{v_1, v_2, \dots, v_{d+1}\}$ and $\{w_1, w_2, \dots, w_{d+1}\}$.

The volume of $S(\mathcal{F})$ is maximal, so each K_i has to touch its respective facet of $S(\mathcal{F})$.

Assume the contrary: K_i does not intersect $s(\mathcal{F})$.

Let C_i be a cone with vertex w_i spanned by rays $w_i w_j$ ($j \neq i$). K_i cannot intersect C_i because these sets are separated by $\text{bd } H_i$ and could only have intersection in $w_i \in s(\mathcal{F})$.

Then there exists a halfspace $H'_i \supseteq K_i$ such that $H'_i \cap C_i = \emptyset$. The family of halfspaces $(\mathcal{H} \setminus \{H_i\}) \cup \{H'_i\}$ is non-intersecting ($\bigcap_{j \neq i} H_j \subseteq C_i$) and is a test family. By Lemma 5

$$\text{vol } S(H_1, \dots, H'_i, \dots, H_{d+1}) > \text{vol } S(\mathcal{F})$$

and we have a contradiction.

Now take $K \in \mathcal{F} \setminus \mathcal{K}$. Assume that $K \cap s(\mathcal{F}) = \emptyset$.

There exists a halfspace $H \supseteq K$ that does not intersect $s(\mathcal{F})$. $H \not\supseteq S(\mathcal{F})$ and we find the farthest from H vertex of $S(\mathcal{F})$ and denote it v_i .

Then $\bigcap_{j \neq i} H_j$ is a cone spanned by the rays that has their origins at v_i and do not intersect H . Hence $H \cap \bigcap_{j \neq i} H_j = \emptyset$ and the family $(\mathcal{H} \setminus \{H_i\}) \cup \{H\}$ has no common point. Considering simplices $S((\mathcal{H} \setminus \{H_i\}) \cup \{H\})$ and $S(\mathcal{F})$ we again come to contradiction by Lemma 5. \square

We need another lemma to prove Theorem 4:

Lemma 6. *Suppose we have a simplex S in \mathbb{R}^d ($d \geq 5$), its outer halfspaces corresponding to facets being $\mathcal{H} = \{H_1, H_2, \dots, H_{d+1}\}$. Let a ball B of radius R together with the family \mathcal{H} give a family with Π_d property. Then the radius r of the ball inscribed in S satisfies the inequality*

$$r \leq \frac{1}{\lfloor \frac{d+1}{2} \rfloor - 1} R \leq 1/2R.$$

Proof. Let the vertices of S be $\{v_1, v_2, \dots, v_{d+1}\}$. Consider the orthogonal projection $p : \mathbb{R}^d \rightarrow V$ taking pairs $\{v_1, v_2\}$, $\{v_3, v_4\}$, and so on to single points. If $d+1$ is odd let p take v_{d-1}, v_d, v_{d+1} into one point, otherwise, p takes pairs into single points. We have a simplex $S' = p(S)$ with $d'+1 = \lfloor \frac{d+1}{2} \rfloor$ vertices, let its outer halfspaces of facets be $\mathcal{H}' = \{H'_1, H'_2, \dots, H'_{d'+1}\}$. We also have a ball $B' = p(B)$.

In the barycentric coordinates $\{x_1, x_2, \dots, x_{d+1}\}$ of S and $\{y_1, y_2, \dots, y_{d'+1}\}$ of S' the map p is given by:

$$\begin{aligned} y_1 &= x_1 + x_2 \\ y_2 &= x_2 + x_3 \\ &\dots \\ y_{d'+1} &= x_d + x_{d+1} \quad \text{or} \quad y_{d'+1} = x_{d-1} + x_d + x_{d+1}. \end{aligned}$$

It is easy to see that B' has a common point with every family $\mathcal{H}' \setminus \{H'_i\}$. These common points form a simplex containing S' , hence B' contains S' .

Then we make a homothety with center at the mass center of S' and scale ratio $-\frac{1}{d'}$. It takes B' to the ball B'' of radius $\frac{1}{d'}R$ that intersects all facets of S' . So the radius of the inscribed ball of S' cannot be larger than $\frac{1}{d'}R$, since the inscribed ball is the ball of minimal radius intersecting all the facets of the simplex.

Hence the radius of the inscribed ball of S cannot be larger than $\frac{1}{d'}R$ too. \square

3. CONCAVE SIMPLICES OF CURVATURE RADIUS R

We give some definitions:

Definition. Let a family $\{B_1, B_2, \dots, B_{d+1}\}$ of euclidean balls of radius R and centers $\{o_1, o_2, \dots, o_{d+1}\}$ in \mathbb{R}^d have the following property: every d balls have a common point while the whole family has no common point. In this case we call the set

$$\text{cl} \left(\text{conv}\{o_1, o_2, \dots, o_{d+1}\} \setminus \bigcup_{i=1}^{d+1} B_i \right)$$

a *concave simplex of curvature radius R* .

In the plane we consider arbitrary norm $\|\cdot\|$ and give a non-euclidean version of the above definition:

Definition. Let a family $\{B_1, B_2, B_3\}$ of balls of radius R and centers $\{o_1, o_2, o_3\}$ w.r.t. norm $\|\cdot\|$ in the plane have the following property: every 2 balls intersect while the whole family has no common point. The set

$$\text{cl} \left(\text{conv}\{o_1, o_2, o_3\} \setminus \bigcup_{i=1}^3 B_i \right)$$

is called a *concave simplex of curvature radius R* in norm $\|\cdot\|$.

By Sperner's lemma the simplices defined above are nonempty, otherwise the family should have a common point.

We could define a concave simplex for arbitrary norm in any dimension, but in general they do not have the properties we want because the bounded connected component of $\mathbb{R}^d \setminus \bigcup_{i=1}^{d+1} B_i$ does not have to lie in $\text{conv}\{o_1, o_2, \dots, o_{d+1}\}$ for $d > 2$.

We prove several lemmas about concave simplices of curvature radius R . Unless specially noted, our reasoning is valid for both the cases of an arbitrary two-dimensional norm and the euclidean norm in \mathbb{R}^d .

Definition. Let T be a concave simplex in \mathbb{R}^d . A *vertex* of T is a point on its boundary that belongs to boundaries of exactly d balls that determine T .

Lemma 7. *Let T be a concave simplex of curvature radius R . Then*

- 1) *int T does not intersect the boundary of $S = \text{conv}\{o_1, o_2, \dots, o_{d+1}\}$;*
- 2) *T is contained in the convex hull of its vertices;*
- 3) *the number of vertices of T is $d + 1$.*

Proof. The first statement can be deduced from the fact that each facet of S is contained in a union of balls of radius R with centers in the vertices of the facet.

Each extremal point of T has to be its vertex, hence T is contained in the convex hull of its vertices.

Each vertex of T corresponds to the intersection of d spheres of radius R . Centers of these spheres make a facet F of S . If the spheres have two intersection points then their intersection points lie on different sides of the hyperplane of F , so only one of the points can be a vertex of T . In the case of the plane, when the balls are not strictly convex, the intersection of the spheres can be a line segment. But in this case a vertex of T is necessarily in the end of the segment and one of the ends is on the other side of F .

Finally we have no more than $d+1$ vertices of T , their number cannot be less because $\text{int } T \neq \emptyset$. \square

Lemma 8. *A concave simplex T of curvature radius R in two-dimensional case has diameter no more than R in the norm $\|\cdot\|$; in d -dimensional case it has diameter no more than $\frac{2}{\sqrt{d^2-1}}R < R$.*

Proof. In two-dimensional case T lies in the triangle formed by midpoints of sides of triangle $o_1o_2o_3$, therefore its diameter does not exceed R .

In the case of euclidean balls consider the point o equidistant from o_1, o_2, \dots, o_{d+1} . It is not contained in any of the balls $B_{o_i}(R)$ and is

contained in $\text{conv}\{o_1, o_2, \dots, o_{d+1}\}$, hence, $o \in T$. The result of Danzer (see Theorem 6.8 in [1]) implies that $|oo_i| \leq \frac{d}{\sqrt{d^2-1}}R$.

The length of any tangent from o to the ball $B_{o_i}(R)$ does not exceed $\frac{1}{\sqrt{d^2-1}}R$ and any line segment from o to a point on $\text{bd } B_{o_i}(R)$ that does not intersect $\text{int } B_{o_i}(R)$ has length no more than $\frac{1}{\sqrt{d^2-1}}R$.

Every vertex v of T lies on the radical axis of some d balls, this radical axis passes through o , thus all segments ov lie in T and do not intersect $\text{int } B_{o_i}(R)$. Hence all segments ov have length no more than $\frac{1}{\sqrt{d^2-1}}R$, which implies the statement of the lemma. \square

Lemma 9. *A ball of radius $R' \geq R$ intersects a concave simplex T of curvature radius R iff it contains some vertex of T .*

Proof. Consider all the balls of radius R' that intersect T . Denote the set of their centers by X .

Consider all the balls of radius R' that contain some vertex of T . Denote the set of their centers by Y . It is clear to see that

$$Y = \bigcup_{i=1}^{d+1} B_{o_i}(R').$$

By Lemma 8 $\text{diam } T \leq R$ and each ball $B_{o_i}(R')$ contains T . Thus Y is star-shaped with any center in T . Similarly, X is star-shaped with any center in T . To prove the inclusion $X \subseteq Y$ we only have to prove that $\text{bd } X \subseteq Y$.

Let $x \in \text{bd } X$ and $B = B_x(R')$. Clearly $B \cap \text{int } T = \emptyset$ and $B \cap \text{bd } T \neq \emptyset$.

Consider the case of the euclidean norm first.

Let $y \in \text{bd } X \cap B$. If y is not a vertex of T then it lies on at most $d-1$ spheres of radius R that determine T . Let their centers be o_1, \dots, o_k , $k \leq d-1$. Considering the linear approximation of T and B in some vicinity of y we see that $\text{int } X \cap \text{int } B = \emptyset$ implies that

$$x - y = \sum_{i=1}^k \alpha_i (o_i - y) \quad \forall i = 1, \dots, k \quad \alpha_i \geq 0.$$

If there is only one index i such that $\alpha_i \neq 0$ then for such i we have $B \supseteq B_{o_i}(R)$, in this case B contains at least d vertices of T that lie on $\text{bd } B_{o_i}(R)$.

Otherwise, consider the affine subspace

$$L = \{p \in \mathbb{R}^d : |p - o_1| = |p - o_2| = \dots = |p - o_k|\}.$$

We have $\dim L \geq 2$, $y \in L$. All intersections $L \cap B_{o_i}(R)$ ($i = 1, \dots, k$) are the same ball $B' \subset L$ and $L \cap B$ is another ball $B'' \subset L$.

The direction of vector $x - y$ does not coincide with any of $o_i - y$ but lies in their cone hull. All the angles between $o_i - y$ and L are equal to some α , so the angle between $x - y$ and L is less than α , hence the radius of B' is less than the radius of B'' .

The intersection $\text{int } T \cap L$ in some vicinity of y coincides with $L \setminus B'$ and B'' intersects $L \setminus B'$ in any vicinity of y , this is a contradiction with $B \cap \text{int } T = \emptyset$.

The case of $d = 2$ and arbitrary norm with smooth and strictly convex ball is made in the same manner as above, in this case $k = 1$ and we do not have to use equidistant set (which is not an affine subspace in general). Then we can approximate any norm by a norm with smooth and strictly convex ball and proceed by going to a limit. \square

Lemma 10. *R -lower convex set intersects a concave simplex T of curvature radius R iff it contains a vertex of T .*

Proof. Trivially deduced from Lemma 9. \square

4. PROOFS OF THE THEOREMS

Proof of Theorems 2 and 3. If $\tau(\mathcal{F}) = 1$ the statement is true. Otherwise by Lemma 3 we have $S = S(\mathcal{F})$ and $s = s(\mathcal{F})$. We call elements of \mathcal{F} balls.

Denote the maximal radius of the ball in \mathcal{F} by R .

Take the balls K_1, K_2, \dots, K_{d+1} corresponding to S , they touch the facets of S in the respective vertices of s . Consider the balls $K'_1, K'_2, \dots, K'_{d+1}$ with radius R touching the respective facets of S in vertices of s .

It can be easily seen that $K'_i \supseteq K_i$ for all $i = 1, \dots, d + 1$. Each d of K'_i have a common point and they all do not have a common point, hence they define a concave simplex T of curvature radius R , obviously $T \supseteq S$. Let the homothety with scale ratio $-1/d$ that takes S to s take T to T' , the latter concave simplex has curvature radius R/d .

By Lemma 4 any $K \in \mathcal{F}$ intersects s and therefore intersects T' , its radius being at least R/d . Hence by Lemma 9 K contains one of $d + 1$ vertices of T' . \square

Proof of Theorem 4. If \mathcal{F} has a common point it is nothing to prove.

Otherwise, consider the ball $B(\mathcal{F})$ of minimal radius r intersecting every ball in \mathcal{F} . This is a well-known consequence of Helly's theorem that this ball is the ball of minimal radius intersecting $d + 1$ balls of some subfamily $\mathcal{F}' = \{B_1, B_2, \dots, B_{d+1}\} \subseteq \mathcal{F}$ (remember that \mathcal{F} has Π_d property) and each intersection $B(\mathcal{F}) \cap B_i$ is exactly one point v_i .

Let H_i be the outer support halfspace for $B(\mathcal{F})$ in the point v_i . Then $S = \mathbb{R}^d \setminus \bigcup_{i=1}^{d+1} \text{int } H_i$ is a simplex with inscribed ball $B(\mathcal{F})$.

Let the ball $B \in \mathcal{F}$ have minimal radius R . Consider the case $d \geq 5$ first. Obviously, B and S satisfy the conditions of Lemma 6 and we have $r \leq 1/2R$.

Note that a ball of radius r can be put into a concave simplex of curvature radius

$$R' = \frac{1}{\frac{d}{\sqrt{d^2-1}} - 1} r = (d\sqrt{d^2-1} + d^2 - 1)r \leq 2d^2r \leq d^2R.$$

Thus the subfamily of balls in \mathcal{F} with radii $\geq d^2R$ has a transversal of cardinality $d+1$, which is the set of vertices of this concave simplex. Other balls in \mathcal{F} can be partitioned into two subfamilies with radii from R to dR and from dR to d^2R , by Theorem 3 these subfamilies have $(d+1)$ -transversals. In total we obtain a $3(d+1)$ -transversal for \mathcal{F} .

In the case $d \leq 4$ we note that all balls in \mathcal{F} intersect the smallest ball in \mathcal{F} of radius R , the latter can be put into a concave simplex of curvature radius

$$(d\sqrt{d^2-1} + d^2 - 1)R \leq d^3R.$$

The vertices of this concave simplex make a transversal for balls in \mathcal{F} with radii $\geq d^3R$. Other balls can be partitioned into three families with $(d+1)$ -transversals to obtain the transversal for \mathcal{F} of size $4(d+1)$. \square

Proof of Theorem 5. We omit the obvious case $\tau(\mathcal{F}) = 1$ and consider $S = S(\mathcal{F})$ and $s = s(\mathcal{F})$.

Note that any simplex $K \in \mathcal{F}$ is a negative homothet of S and a positive homothet of s . This can be deduced from considering the sets of outer and inner normals to facets of S , K , and s .

Assume that K does not contain any vertex of s .

If K intersects some d facets of s it has to contain their intersection, which is a vertex of s . Hence there are two facets of s that K does not intersect. Let these facets correspond to the halfspaces H_1 and H_2 from the family $\{H_1, H_2, \dots, H_{d+1}\}$ of outer support halfspaces for facets of S .

Denote the translate of halfspace H_i containing the respective facet of s in its boundary by G_i .

K is a homothet of s , intersects s , and does not intersect the facet $\text{bd } G_1 \cap s$. Hence $K \subseteq G_1$. Similarly $K \subseteq G_2$. We show that the intersection

$$G_1 \cap G_2 \cap H_3 \cap \dots \cap H_{d+1}$$

is either empty or consists of one vertex of s , the latter is possible when $d = 2$ only. For all $i = 1, \dots, d + 1$ $H_i \subseteq G_i$ and therefore

$$G_1 \cap G_2 \cap H_3 \cap \dots \cap H_{d+1} \subseteq G_1 \cap G_2 \cap G_3 \cap \dots \cap G_{d+1} = s.$$

The simplex s intersects halfspaces H_3, \dots, H_{d+1} at one point each, hence

$$G_1 \cap G_2 \cap H_3 \cap \dots \cap H_{d+1}$$

can be non-empty when $d = 2$ only, in this case it consists of one vertex of s .

Note that K does not contain any vertex of s and

$$K \cap \bigcap_{i=3}^{d+1} K_i \subseteq K \cap \bigcap_{i=3}^{d+1} H_i = \emptyset,$$

which is a contradiction with Π_d property. □

We need another lemma to prove theorem 6.

Lemma 11. *If a halfspace H contains an R -upper convex set K then there exists a ball B of radius R such that $K \subseteq B \subseteq H$.*

The author cannot give the exact reference to the first proof of this fact, a proof of this fact can be found in [5].

Proof of Theorem 6. We omit the case $\tau(\mathcal{F}) = 1$ and consider $S = S(\mathcal{F})$ and $s = s(\mathcal{F})$.

Take the sets K_1, K_2, \dots, K_{d+1} in \mathcal{F} that correspond to S and consider the balls $K'_1, K'_2, \dots, K'_{d+1}$ with the following properties: the radius of K'_i is dR , $K'_i \supseteq K_i$, and $K'_i \cap S = K_i \cap S$. Such K'_i can be found by Lemma 11 if we consider for each K_i its respective outer support halfspace H_i for S .

The balls $K'_1, K'_2, \dots, K'_{d+1}$ have Π_d property and have no common point, so they make a concave simplex T of curvature radius dR and $T \supseteq S$. Let the homothety that takes S to s take T to T' , the latter has curvature radius R .

By Lemma 4 any $K \in \mathcal{F}$ intersects s and therefore intersects T' . By Lemma 10 K contains one of $d + 1$ vertices of T' . □

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